

Q. 1 a) Let $v_1 = (2, -1, 3, 2)$, $v_2 = (-1, 1, 1, -3)$ and $v_3 = (1, 1, 9, -5)$ be three vectors of the space \mathbb{R}^4 . Does $(3, -1, 0, -1) \in \text{span}\{v_1, v_2, v_3\}$? Justify your answer.

Solⁿ:

Let

$$\begin{aligned} (3, -1, 0, -1) &= x(2, -1, 3, 2) + y(-1, 1, 1, -3) \\ &\quad + z(1, 1, 9, -5) \\ &= (2x - y + z, -x + y + z, 3x + y + 9z, 2x - 3y - 5z) \end{aligned}$$

where $x, y, z \in \mathbb{R}$

- (1)

$$\left. \begin{aligned} 2x - y + z &= 3 \\ -x + y + z &= -1 \\ 3x + y + 9z &= 0 \\ 2x - 3y - 5z &= -1 \end{aligned} \right\} \textcircled{2}$$

Now $Ax = B$

where $A = \begin{bmatrix} 2 & -1 & 1 \\ -1 & 1 & 1 \\ 3 & 1 & 9 \\ 2 & -3 & -5 \end{bmatrix}$ $x = \begin{bmatrix} x \\ y \\ z \end{bmatrix}$ $B = \begin{bmatrix} 3 \\ -1 \\ 0 \\ 1 \end{bmatrix}$

$$[A/B] = \left[\begin{array}{ccc|c} 2 & -1 & 1 & 3 \\ -1 & 1 & 1 & -1 \\ 3 & 1 & 9 & 0 \\ 2 & -3 & -5 & -1 \end{array} \right]$$

$$R_1 \leftrightarrow R_2$$

$$\Rightarrow [A|B] = \left[\begin{array}{ccc|c} -1 & 1 & 1 & -1 \\ 2 & -1 & 1 & 3 \\ 3 & 1 & 9 & 0 \\ 2 & -3 & -5 & -1 \end{array} \right]$$

$$R_1 \rightarrow (-1)R_1$$

$$\Rightarrow [A|B] = \left[\begin{array}{ccc|c} 1 & -1 & -1 & 1 \\ 2 & -1 & 1 & 3 \\ 3 & 1 & 9 & 0 \\ 2 & -3 & -5 & -1 \end{array} \right]$$

$$R_2 \rightarrow R_2 - 2R_1, \quad R_3 \rightarrow R_3 - 3R_1, \quad R_4 \rightarrow R_4 - 2R_1$$

$$\Rightarrow [A|B] = \left[\begin{array}{ccc|c} 1 & -1 & -1 & 1 \\ 0 & 1 & 3 & -5 \\ 0 & 4 & 12 & -3 \\ 0 & -1 & -3 & -3 \end{array} \right]$$

$$R_3 \rightarrow \left(\frac{1}{4}\right)R_3 \quad R_4 \rightarrow (R_4 + R_2)$$

$$\Rightarrow [A|B] = \left[\begin{array}{ccc|c} 1 & -1 & -1 & 1 \\ 0 & 1 & 3 & -5 \\ 0 & 1 & 3 & -3/4 \\ 0 & 0 & 0 & -8 \end{array} \right]$$

$$R_3 \rightarrow R_3 - R_2$$

$$\Rightarrow [A|B] = \left[\begin{array}{ccc|c} 1 & -1 & -1 & 1 \\ 0 & 1 & 3 & -5 \\ 0 & 0 & 0 & 17/4 \\ 0 & 0 & 0 & -8 \end{array} \right]$$

Clearly, $\rho(A) = 2, \rho(A|B) = 4 \therefore \rho(A) < \rho(A|B)$

\therefore The given equation has no solution.

Hence, $(3, -1, 0, -1) \notin \text{span}\{v_1, v_2, v_3\}$

Q. 1. b)

Find the rank and nullity of the linear transformation:

$T: \mathbb{R}^3 \rightarrow \mathbb{R}^3$ given by

$$T(x, y, z) = (x+z, x+y+2z, 2x+y+3z)$$

Solⁿ:

Given $T: \mathbb{R}^3 \rightarrow \mathbb{R}^3$ and given linear transformation

$$T(x, y, z) = (x+z, x+y+2z, 2x+y+3z)$$

i) For null space

$$T(x, y, z) = 0$$

$$(x+z, x+y+2z, 2x+y+3z) = 0$$

$$x+z=0 \quad - \textcircled{1}$$

$$x+y+2z=0 \quad - \textcircled{2}$$

$$2x+y+3z=0 \quad - \textcircled{3}$$

from $\textcircled{1}$, $x = -z$,

$$\textcircled{2} \Rightarrow x+y-2z=0 \Rightarrow x=y$$

Hence we get the null space

$$N(T) = \{x(1, 1, -1) \mid x \in \mathbb{R}\}$$

\therefore Nullity = 1 (as no. of vector in basis of $N(T)$)

ii) By Rank - Nullity theorem,

$$\dim \mathbb{R}^3 = \text{rank}(T) + \text{Nullity}(T)$$

$$3 = \text{rank}(T) + 1$$

$$\therefore \text{Rank}(T) = 2$$

Hence Rank(T) = 2 & Nullity(T) = 1

Q. 1 c)

Find the values of p and q for which

$$\lim_{x \rightarrow 0} \frac{x(1+p \cos x) - q \sin x}{x^3}$$
 exists and equals 1.

Solⁿ:

$$\lim_{x \rightarrow 0} \frac{x(1+p \cos x) - q \sin x}{x^3} \left(\frac{0}{0} \right) \text{ Indeterminate fundamental form}$$

\therefore Applying L'Hospital's rule

$$\lim_{x \rightarrow 0} \frac{\frac{d}{dx} [x(1+p \cos x) - q \sin x]}{\frac{d}{dx} (x^3)} = 1$$

$$\therefore \lim_{x \rightarrow 0} \frac{1 + p \cos x - px \sin x - q \cos x}{3x^2} = 1$$

$$\therefore \lim_{x \rightarrow 0} \frac{1 + (p-q) \cos x - xp \sin x}{3x^2} = 1$$

to satisfy limit $1+p-q=0$

$$\Rightarrow \boxed{p+1=q} \quad - (1)$$

Applying L'Hospital's rule

$$\lim_{x \rightarrow 0} \frac{-(p-q) \sin x - p \sin x - xp \cos x}{6x} = 1$$

$$\lim_{x \rightarrow 0} \frac{(q-p) \sin x - p \sin x - xp \cos x}{6x} = 1$$

$$\lim_{x \rightarrow 0} \frac{(q-2p) \sin x - px \cos x}{6x} = 1$$

$$\lim_{x \rightarrow 0} \frac{(q-2p)}{6} \cdot \frac{\sin x}{x} - \lim_{x \rightarrow 0} \frac{p}{6} \cos x = 1$$

$$\Rightarrow \frac{q-2p}{6} - \frac{p}{6} = 1$$

$$\Rightarrow q - 3p = 6$$

$$q = 3p + 6$$

$$\boxed{q = 3(p+2)} \quad - (2)$$

$$p - q = -1$$

$$- 3p - q = -6$$

$$\hline -2p = 5$$

$$\therefore \boxed{p = -\frac{5}{2}} \quad \text{and}$$

$$q = 1 - 5/2$$
$$\boxed{q = -\frac{3}{2}}$$

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Q. 1 d)

Examine the convergence of the integral

$$\int_0^1 \frac{\log x}{1+x} dx$$

Solⁿ:

Method 1:

$$f(x) = \frac{\log x}{1+x} dx$$

Clearly, f is unbounded at $x=0$

$$I = \int_0^1 \frac{\log x}{1+x} dx \quad \text{--- (1)}$$

Only point of infinite discontinuity is

$$\underline{x=0}$$

$$\therefore \lim_{x \rightarrow 0} x^\mu f(x) = \lim_{x \rightarrow 0} x^\mu \frac{\log x}{1+x} = 0, \text{ if } \mu > 0$$

Hence we choose $0 < \mu < 1$, then by μ test I is convergent.

Method 2:

Since $\frac{\log x}{1+x}$ is negative on $(0, 1]$,

$$\text{we take } f(x) = \frac{-\log x}{1+x}$$

Here '0' is the only point of infinite discontinuity of f on $[0, 1]$

$$\text{take } g(x) = \frac{1}{x^\mu}$$

$$\lim_{x \rightarrow 0^+} \frac{f(x)}{g(x)} = \lim_{x \rightarrow 0^+} \frac{-x^n \log x}{1+x} = 0, \text{ if } n > 0$$

Taking n between 0 and 1, the integral $\int_0^1 g(x) dx$ is convergent.

\therefore By comparison test,

$\int_0^1 f(x) dx$ is convergent.

Hence $\int_0^1 \frac{\log x}{1+x} dx$ is convergent

Q. 1 e)

A variable plane which is at a constant distance $3p$ from the origin O cuts the axes in the points A, B, C respectively. Show that the locus of the centroid of the tetrahedron $OABC$ is

$$g \left(\frac{1}{x^2} + \frac{1}{y^2} + \frac{1}{z^2} \right) = \frac{16}{p^2}$$

Solⁿ:

Let the equation of the variable plane be

$$\frac{x}{a} + \frac{y}{b} + \frac{z}{c} = 1 \quad - (1)$$

It is given that this plane is at a distance ' $3p$ ' from $(0,0,0)$

$$\therefore 3p = \frac{1}{\sqrt{\left(\frac{1}{a}\right)^2 + \left(\frac{1}{b}\right)^2 + \left(\frac{1}{c}\right)^2}}$$

$$\text{or } \frac{1}{9p^2} = \frac{1}{a^2} + \frac{1}{b^2} + \frac{1}{c^2} \quad - (2)$$

Also the plane (1) meets the axes in A, B and C . So the co-ordinates O, A, B and C are $(0,0,0), (a,0,0), (0,b,0)$ and $(0,0,c)$ respectively.

Let (x, y, z) be the centroid of the tetrahedron $OABC$, then

$$x = \frac{1}{4} (0 + a + 0 + 0)$$

$$x = \frac{1}{4} a$$

Similarly $y = \frac{1}{4} b$ and $z = \frac{1}{4} c$

or $a = 4x, b = 4y, c = 4z$

Substituting these values of a, b and c in (2), we have the required locus as

$$\frac{1}{9p^2} = \frac{1}{16x^2} + \frac{1}{16y^2} + \frac{1}{16z^2}$$

or
$$g \left(\frac{1}{x^2} + \frac{1}{y^2} + \frac{1}{z^2} \right) = \frac{16}{p^2}$$

Hence proved.

Q. 2 a)

If the matrix of a linear transformation $T: \mathbb{R}^3 \rightarrow \mathbb{R}^3$ relative to the basis

$$\{(1, 0, 0), (0, 1, 0), (0, 0, 1)\} \text{ is } \begin{bmatrix} 1 & 1 & 2 \\ -1 & 2 & 1 \\ 0 & 1 & 3 \end{bmatrix}$$

then find the matrix of T relative to the basis $\{(1, 1, 1), (0, 1, 1), (0, 0, 1)\}$

Solⁿ:

Let $B = \{(1, 0, 0), (0, 1, 0), (0, 0, 1)\}$

given that $[T]_B = \begin{bmatrix} 1 & 1 & 2 \\ -1 & 2 & 1 \\ 0 & 1 & 3 \end{bmatrix}$

let any $\alpha(x, y, z) \in \mathbb{R}^3$ can be expressed as

$$(x, y, z) = x(1, 0, 0) + y(0, 1, 0) + z(0, 0, 1)$$

$$T(x, y, z) = xT(1, 0, 0) + yT(0, 1, 0) + zT(0, 0, 1) \quad \text{--- (1)}$$

$$T(1, 0, 0) = (1, -1, 0)$$

$$T(0, 1, 0) = (1, 2, 1)$$

$$T(0, 0, 1) = (2, 1, 3)$$

} from $[T]_B$
given

$$\therefore (1) \Rightarrow T(x, y, z) = x(1, -1, 0) + y(1, 2, 1) + z(2, 1, 3)$$

$$\boxed{T(x, y, z) = (x + y + 2z, -x + 2y + z, y + 3z)}$$

is required transformation

Let $B' = \{(1, 1, 1), (0, 1, 1), (0, 0, 1)\}$

Let $(x, y, z) = a(1, 1, 1) + b(0, 1, 1) + c(0, 0, 1)$

$$(x, y, z) = (a, a + b, a + b + c)$$

$$\therefore a = x$$

$$a + b = y \Rightarrow b = y - x$$

$$a + b + c = z \Rightarrow c = z - y$$

$$\therefore (x, y, z) = x(1, 1, 1) + (y - x)(0, 1, 1) + (z - y)(0, 0, 1)$$

We need to express with respect to B'

$$T(1, 1, 1) = (4, 2, 4) = 4(1, 1, 1) - 2(0, 1, 1) + 2(0, 0, 1)$$

$$T(0, 1, 1) = (3, 3, 4) = 3(1, 1, 1) + 0(0, 1, 1) + 1(0, 0, 1)$$

$$T(0, 0, 1) = (2, 1, 3) = 2(1, 1, 1) - 1(0, 1, 1) + 2(0, 0, 1)$$

Hence matrix of linear transformation is

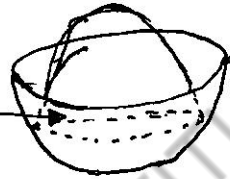
$$[T]_{B'} = \begin{bmatrix} 4 & 3 & 2 \\ -2 & 0 & -1 \\ 2 & 1 & 2 \end{bmatrix}$$

is required solution.

Q. 2. b) Evaluate the triple integral which gives the volume of the solid enclosed between the two paraboloids $Z = 5(x^2 + y^2)$ and $Z = 6 - 7x^2 - y^2$.

Solⁿ:

To find volume of solid enclosed betⁿ these two paraboloids



The bounded region of the above paraboloids is

$$Z = 5x^2 + 5y^2 = 6 - 7x^2 - y^2$$

$$12x^2 + 6y^2 = 6$$

$$2x^2 + y^2 = 1$$

is intersection of two curves.

Thus volume of region

$$V = \int_{-1/\sqrt{2}}^{1/\sqrt{2}} \int_{-\sqrt{1-2x^2}}^{\sqrt{1-2x^2}} \int_{5x^2+5y^2}^{6-7x^2-y^2} 1 \, dx \, dy \, dz \quad \text{--- (1)}$$

Proceeding with cylindrical co-ordinate

$$x = \frac{r}{\sqrt{2}} \cos \theta \quad y = r \sin \theta \quad z = z$$

$$dx \, dy \, dz = \frac{r}{\sqrt{2}} \, dr \, d\theta \, dz$$

On reducing the equation (1)

$$V = \int_0^{2\pi} \int_0^1 \int_{\frac{5}{2}r^2 \cos^2 \theta + 5r^2 \sin^2 \theta}^{6 - \frac{7}{2}r^2 \cos^2 \theta - r^2 \sin^2 \theta} 1 \cdot \frac{r}{\sqrt{2}} dr d\theta dz$$

$$= \frac{1}{\sqrt{2}} \int_0^{2\pi} \int_0^1 (6 - 6r^2) r dr d\theta$$

$$= \frac{1}{\sqrt{2}} 2\pi \int_0^1 (6 - 6r^2) r dr$$

$$= \frac{1}{\sqrt{2}} 2\pi \left(\frac{6r^2}{2} - \frac{6r^4}{4} \right) \Big|_0^1$$

$$= \frac{2\pi}{\sqrt{2}} \left(3 - \frac{3}{2} \right)$$

$$= \frac{2\pi}{\sqrt{2}} \cdot \frac{3}{2}$$

$$= \frac{3\pi}{\sqrt{2}}$$

$$\therefore \boxed{V = \frac{3\pi}{\sqrt{2}}}$$

Q. 2 c) i)

Show that the equation $2x^2 + 3y^2 - 8x + 6y - 12z + 11 = 0$ represents an elliptic paraboloid. Also find its principal axis and principal planes.

Solⁿ:

$$2x^2 + 3y^2 - 8x + 6y - 12z + 11 = 0$$

$$a = 2 \quad b = 3 \quad c = 0$$

$$f = 0 \quad g = 0 \quad h = 0$$

$$u = -4 \quad v = 3 \quad w = -6 \quad d = 11$$

We know that the discriminating cubic equation is

$$\begin{vmatrix} a-\lambda & h & g \\ h & b-\lambda & f \\ g & f & c-\lambda \end{vmatrix} = 0$$

$$\Rightarrow \begin{vmatrix} 2-\lambda & 0 & 0 \\ 0 & 3-\lambda & 0 \\ 0 & 0 & -\lambda \end{vmatrix} = 0$$

$$\lambda (\lambda - 3) (\lambda - 2) = 0$$

$$\lambda = 0, \lambda = 2, \lambda = 3$$

Now putting $\lambda = 0$ in the determinant given by (1) and associating each row with l_3, m_3, n_3 we have

$$l_3 = 0, m_3 = 0, n_3 \cdot 0 = 0 \quad n_3 \neq 0$$

because $l^2 + m^2 + n^2 = 1$

$$\therefore n = 1$$

Now $k = ul_3 + vm_3 + wn_3$

$$k = -4 \times 0 + 3 \times 0 + -6 \times 1$$

$$\boxed{k = -6}$$

Required reduced eqⁿ is

$$\lambda_1 x^2 + \lambda_2 y^2 + 2kz = 0$$

$$2x^2 + 3y^2 - 12z = 0$$

$$\boxed{\frac{x^2}{3} + \frac{y^2}{2} = 2z}$$

which represent an elliptical paraboloid as both λ_1 and λ_2 are positive

Also if $F(x, y, z) = 0$ be the given surface then the co-ordinate of its vertex are given by solving any two of these equations.

$$\frac{\partial F / \partial x}{l_3} = \frac{\partial F / \partial y}{m_3} = \frac{\partial F / \partial z}{n_3} = 2k$$

$$\text{and } k(l_3x + m_3y + n_3z) + ux + vy + wz + d = 0$$

$$F \equiv 2x^2 + 3y^2 - 8x + 6y - 12z + 11 = 0$$

$$\frac{\partial F}{\partial x} = 4x - 8 ; \frac{\partial F}{\partial y} = 6y + 6 ; \frac{\partial F}{\partial z} = -12$$

$$k(l_3x + m_3y + n_3z) + ux + vy + wz + d = 0$$

$$-12(0 \cdot x + 0 \cdot y + 1 \cdot z) - 4x + 3y - 6z + 11 = 0$$

$$-12z - 4x + 3y - 6z + 11 = 0$$

$$-4x + 3y - 18z + 11 = 0$$

$$\frac{\frac{\partial F}{\partial x}}{l_3} = \frac{\frac{\partial F}{\partial y}}{m_3} = \frac{\frac{\partial F}{\partial z}}{n_3} = 2k$$

$$\frac{4x-8}{0} = \frac{6y+6}{0} = \frac{-12}{1} = 2(-12)$$

$$\Rightarrow 4x-8=0 \mid 6y+6=0 \mid -8-3-18z+11=0$$

$$\Rightarrow x=2 \mid y=-1 \mid -18z=0$$

$$\Rightarrow z=0$$

\therefore Vertex is $(2, -1, 0)$

Principal axis equation is

$$\frac{x-2}{0} = \frac{y+1}{0} = \frac{z-0}{1}$$

Principal plane equation is given by
 $\lambda(lx + my + nz) + (ul + vm + wn) = 0$

for $\lambda = 2$:

$$\begin{vmatrix} 0 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & -2 \end{vmatrix} \begin{pmatrix} l_1 \\ m_1 \\ n_1 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}$$

$$m_1 = 0; n_1 = 0 \Rightarrow l_1 = 1$$

$$\lambda (l_1 x + m_1 y + n_1 z) + (u l_1 + v m_1 + w n_1) = 0$$

$$\therefore 2(x) + (-4 \times 1) = 0$$

$$\Rightarrow \boxed{x - 2 = 0}$$

for $\lambda = 3$:

$$\begin{vmatrix} -1 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & -3 \end{vmatrix} \begin{pmatrix} l_2 \\ m_2 \\ n_2 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}$$

$$\Rightarrow -l_2 = 0; n_2 = 0 \Rightarrow m_2 = 1$$

$$\lambda (l_2 x + m_2 y + n_2 z) + (u l_2 + v m_2 + w n_2) = 0$$

$$\therefore 3y + 3 = 0$$

$$\Rightarrow \boxed{y + 1 = 0}$$

\(\therefore\) Required principal plane is

$$\boxed{\begin{matrix} x - 2 = 0 \text{ \& } \\ y + 1 = 0 \end{matrix}}$$

Q. 2 c) ii)

The plane $\frac{x}{a} + \frac{y}{b} + \frac{z}{c} = 1$ meets the co-ordinate axes in A, B, C respectively. Prove that the equation of the cone generated by the lines drawn from the origin O to meet the circle ABC is

$$yz \left(\frac{b}{c} + \frac{c}{b} \right) + zx \left(\frac{c}{a} + \frac{a}{c} \right) + xy \left(\frac{b}{a} + \frac{a}{b} \right) = 0$$

Solⁿ:

The plane ABC is $\frac{x}{a} + \frac{y}{b} + \frac{z}{c} = 1$ - ①

It meets the axes at $A(a, 0, 0)$, $B(0, b, 0)$ & $C(0, 0, c)$.

Since the sphere intercepts a length 'a' on x-axis so it passes through the point $(a, 0, 0)$. Similarly it passes through the points $(0, b, 0)$ & $(0, 0, c)$. Also it passes through the origin i.e. $(0, 0, 0)$

Let the equation of sphere be

$$x^2 + y^2 + z^2 + 2ux + 2vy + 2wz + d = 0 \quad - \text{②}$$

If it passes through $(0, 0, 0)$ then from

$$\text{② we have } d = 0 \quad - \text{③}$$

If ② passes through $(a, 0, 0)$, then we

$$\text{get } a^2 + 2ua + d = 0$$

$$\text{or from ③, } a^2 + 2ua + 0 = 0$$

$$\text{or } u = -\frac{1}{2}a, \text{ as } a \neq 0$$

Similarly as (2) passes through $(0, b, 0)$ and $(0, 0, c)$ we get

$$v = -\frac{1}{2}b \text{ and } w = -\frac{1}{2}c$$

Hence from (2), required equation is

$$x^2 + y^2 + z^2 - ax - by - cz = 0 \quad \text{--- (4)}$$

The required cone is generated by the lines drawn from O to meet the circle ABC (given by (1) and (4) together) and will be homogeneous. So making (4)

homogeneous with the help of (1), we get the required equation as

$$x^2 + y^2 + z^2 - (ax + by + cz) \left(\frac{x}{a} + \frac{y}{b} + \frac{z}{c} \right) = 0$$

$$\text{or } yz \left(\frac{b}{c} + \frac{c}{b} \right) + zx \left(\frac{c}{a} + \frac{a}{c} \right) + xy \left(\frac{b}{a} + \frac{a}{b} \right) = 0$$

Hence proved.

Q. 3 a)

$$\text{Let } A = \begin{bmatrix} 1 & 0 & 0 \\ 1 & 0 & 1 \\ 0 & 1 & 0 \end{bmatrix}$$

i) Verify the Cayley-Hamilton theorem for the matrix A.

ii) Show that $A^n = A^{n-2} + A^2 - I$ for $n \geq 3$, where I is the identity matrix of order 3. Hence find A^{40} .

Solⁿ:

i) Characteristic (Ch.) equation of A is

$$|A - \lambda I| = 0$$

$$\begin{vmatrix} 1-\lambda & 0 & 0 \\ 1 & -\lambda & 1 \\ 0 & 1 & -\lambda \end{vmatrix} = 0$$

$$(1-\lambda)(\lambda^2-1) = 0$$

$$\lambda^3 - \lambda^2 - \lambda + 1 = 0$$

Ch. eqⁿ of A is $\lambda^3 - \lambda^2 - \lambda + 1 = 0$

By Cayley-Hamilton theorem

$$A^3 - A^2 - A + I = 0 \quad \text{--- (1)}$$

$$\text{L.H.S.} = A^3 - A^2 - A + I$$

$$A^2 = A \cdot A = \begin{bmatrix} 1 & 0 & 0 \\ 1 & 0 & 1 \\ 0 & 1 & 0 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 \\ 1 & 0 & 1 \\ 0 & 1 & 0 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 \\ 1 & 1 & 0 \\ 1 & 0 & 1 \end{bmatrix}$$

$$A^3 = A^2 \cdot A = \begin{bmatrix} 1 & 0 & 0 \\ 1 & 1 & 0 \\ 1 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 \\ 1 & 0 & 1 \\ 0 & 1 & 0 \end{bmatrix}$$

$$= \begin{bmatrix} 1 & 0 & 0 \\ 2 & 0 & 1 \\ 1 & 1 & 0 \end{bmatrix}$$

$$\therefore \text{L.H.S.} = A^3 - A^2 - A + I$$

$$= \begin{bmatrix} 1 & 0 & 0 \\ 2 & 0 & 1 \\ 1 & 1 & 0 \end{bmatrix} - \begin{bmatrix} 1 & 0 & 0 \\ 1 & 1 & 0 \\ 1 & 0 & 1 \end{bmatrix} - \begin{bmatrix} 1 & 0 & 0 \\ 1 & 0 & 1 \\ 0 & 1 & 0 \end{bmatrix}$$

$$+ \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

$$= \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}$$

$$= \text{R.H.S.}$$

Hence Cayley-Hamilton theorem is verified.

ii) By Principle of mathematical induction

① $n=3$ $A^3 = A + A^2 - I$ is true by eq ①

② $n=k$ $A^k = A^{k-2} + A^2 - I$ is assume to be true

③ $n=k+1$ $A^{k+1} = A^{k-1} + A^2 - I$

$$\begin{aligned}
 \text{L.H.S.} &= A^{k+1} = A^k \cdot A \\
 &= (A^{k-2} + A^2 - I) A \\
 &= (A^{k-1} + A^3 - A) \\
 &= A^{k-1} + A^2 + A - I - A \\
 &= A^{k-1} + A^2 - I \\
 &= \text{R.H.S.}
 \end{aligned}$$

Hence we proved

$$A^n = A^{n-2} + A^2 - I \quad \text{for } n \geq 3$$

To find A^{40} :

$$\begin{aligned}
 A^{40} &= A^{38} + A^2 - I \\
 &= A^{36} + 2A^2 - 2I \\
 &= A^{34} + 3A^2 - 3I \\
 &\vdots
 \end{aligned}$$

$$= A^2 + 19A^2 - 19I$$

$$A^{40} = 20A^2 - 19I$$

$$= \begin{bmatrix} 20 & 0 & 0 \\ 20 & 20 & 0 \\ 20 & 0 & 20 \end{bmatrix} - \begin{bmatrix} 19 & 0 & 0 \\ 0 & 19 & 0 \\ 0 & 0 & 19 \end{bmatrix}$$

$$\therefore A^{40} = \begin{bmatrix} 1 & 0 & 0 \\ 20 & 1 & 0 \\ 20 & 0 & 1 \end{bmatrix}$$

$$n=4$$

$$A^4 = 2A^2 - I$$

$$\begin{aligned}
 A^8 &= 4A^4 - 4A^2 + I \\
 &= 4(2A^2 - I) - 4A^2 + I \\
 &= 4A^2 - 3I
 \end{aligned}$$

$$\begin{aligned}
 A^{16} &= 16A^4 - 24A^2 + 9I \\
 &= 16(2A^2 - I) - 24A^2 + 9I \\
 &= 8A^2 - 7I
 \end{aligned}$$

$$A^4 = 2A^2 - I$$

$$A^8 = 4A^2 - 3I$$

$$A^{16} = 8A^2 - 7I$$

$$A^{40} = 20A^2 - 19I$$

is required solution

Q. 3. b)

Justify whether $(0,0)$ is an extreme point for the function $f(x,y) = 2x^4 - 3x^2y + y^2$

Solⁿ:

Given $f(x,y) = 2x^4 - 3x^2y + y^2$

$$p = \frac{\partial f}{\partial x} = 8x^3 - 6xy \quad r = \frac{\partial^2 f}{\partial x^2} = 24x^2 - 6y$$

$$q = \frac{\partial f}{\partial y} = -3x^2 + 2y \quad t = \frac{\partial^2 f}{\partial y^2} = 2$$

$$s = \frac{\partial^2 f}{\partial x \partial y} = -6x$$

At point $(0,0)$:

$$\left(\frac{\partial f}{\partial x}\right)_{(0,0)} = 8(0)^3 - 6(0)(0) = 0$$

$$\left(\frac{\partial f}{\partial y}\right)_{(0,0)} = -3(0)^2 + 2(0) = 0$$

$$\left(\frac{\partial^2 f}{\partial x^2}\right)_{(0,0)} = 24(0)^2 - 6(0) = 0$$

$$\left(\frac{\partial^2 f}{\partial x \partial y}\right)_{(0,0)} = -6(0) = 0$$

$$\left(\frac{\partial^2 f}{\partial y^2}\right)_{(0,0)} = 2$$

Now, $rt - s^2 = 0 \times 2 - (0)^2 = 0$

and $r = 0$ at $(0,0)$

$\therefore (0,0)$ does not meet the condition for extreme point using second partial derivative.

It is a critical point but not an extreme point for the given function.

Hence above function neither have maxima nor minima.

Q. 3 c)

Find the equation of the sphere through the circle $x^2 + y^2 + z^2 - 4x - 6y + 2z - 16 = 0$; $3x + y + 3z - 4 = 0$ in the following cases.

- i) the point $(1, 0, -3)$ lies on the sphere.
- ii) the given circle is a great circle of the sphere.

Solⁿ:

We know that, equation of the sphere passing through the circle $S = 0 = P$ is

$$S + \lambda P = 0$$

$$\Rightarrow x^2 + y^2 + z^2 - 4x - 6y + 2z - 16 + \lambda(3x + y + 3z - 4) = 0$$

$$\Rightarrow x^2 + y^2 + z^2 + (3\lambda - 4)x + (\lambda - 6)y + (3\lambda + 2)z - 4\lambda - 16 = 0 \quad \text{--- (1)}$$

i) But given that above sphere passes through the point $(1, 0, -3)$

$$\Rightarrow (1 + 9 - 4 - 6 - 16) + \lambda(3 - 9 - 4) = 0$$

$$-16 + \lambda(-10) = 0$$

$$\lambda = \frac{-16}{-10} = \frac{8}{5}$$

\therefore Sphere equation

$$x^2 + y^2 + z^2 - 4x - 6y + 2z - 16 - \frac{8}{5}(3x + y + 3z - 4) = 0$$

$$5x^2 + 5y^2 + 5z^2 - 44x - 38y - 40z - 48 = 0$$

$$x^2 + y^2 + z^2 - \frac{44}{5}x - \frac{38}{5}y - 8z - \frac{48}{5} = 0$$

Q. 4. a)

Find the rank of the matrix

$$A = \begin{bmatrix} 1 & 2 & -1 & 0 \\ -1 & 3 & 0 & -4 \\ 2 & 1 & 3 & -2 \\ 1 & 1 & 1 & -1 \end{bmatrix}$$

by reducing it to row-reduced echelon form.

Solⁿ:

$$A = \begin{bmatrix} 1 & 2 & -1 & 0 \\ -1 & 3 & 0 & -4 \\ 2 & 1 & 3 & -2 \\ 1 & 1 & 1 & -1 \end{bmatrix}$$

$$R_2 \rightarrow R_2 + R_1, R_3 \rightarrow R_3 - 2R_1, R_4 \rightarrow R_4 - R_1,$$

$$A \sim \begin{bmatrix} 1 & 2 & -1 & 0 \\ 0 & 5 & -1 & -4 \\ 0 & -3 & 5 & -2 \\ 0 & -1 & 2 & -1 \end{bmatrix}$$

$$R_2 \leftrightarrow R_4$$

$$A \sim \begin{bmatrix} 1 & 2 & -1 & 0 \\ 0 & -1 & 2 & -1 \\ 0 & -3 & 5 & -2 \\ 0 & 5 & -1 & -4 \end{bmatrix}$$

$$R_2 \rightarrow (-1)R_2$$

$$A \sim \begin{bmatrix} 1 & 2 & -1 & 0 \\ 0 & 1 & -2 & 1 \\ 0 & -3 & 5 & -2 \\ 0 & 5 & -1 & -4 \end{bmatrix}$$

$$R_3 \rightarrow R_3 + 3R_2, \quad R_4 \rightarrow R_4 - 5R_2$$

$$A \sim \begin{bmatrix} 1 & 2 & -1 & 0 \\ 0 & 1 & -2 & 1 \\ 0 & 0 & -1 & 1 \\ 0 & 0 & 9 & -9 \end{bmatrix}$$

$$R_3 \rightarrow (-1)$$

$$A \sim \begin{bmatrix} 1 & 2 & -1 & 0 \\ 0 & 1 & -2 & 1 \\ 0 & 0 & 1 & -1 \\ 0 & 0 & 9 & -9 \end{bmatrix}$$

$$R_4 \rightarrow R_4 - 9R_3$$

$$A \sim \begin{bmatrix} 1 & 2 & -1 & 0 \\ 0 & 1 & -2 & 1 \\ 0 & 0 & 1 & -1 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

Above matrix is in echelon form. Hence rank of matrix A is non-zero row in echelon form

$$\boxed{R(A) = 3}$$

Q. 4 b)

Trace the curve $y^2(x^2 - 1) = 2x - 1$

Solⁿ: Steps :-

1. Curve is symmetrical about x-axis
2. It does not pass through the origin.
3. Curve meets x-axis in $(\frac{1}{2}, 0)$ and y-axis in $(0, 1)$ and $(0, -1)$
Line $x = \frac{1}{2}$ is tangent to curve at $(\frac{1}{2}, 0)$
4. $x = \pm 1$, $y = 0$ are its only asymptote

$$5. y^2 = \frac{2x-1}{x^2-1}$$

\Rightarrow for $x < -1$ and $\frac{1}{2} < x < 1$, y is imaginary

\therefore Curve lies between region $-1 < x < \frac{1}{2}$ & $x > 1$

$$6. y = \pm \sqrt{\frac{2x-1}{x^2-1}}$$

$$\Rightarrow \frac{dy}{dx} = \pm \left(\frac{-x^2 + x + 1}{(2x-1)^{1/2} (x^2-1)^{3/2}} \right)$$

for $x > 1$, $\frac{dy}{dx} < 0$

$\Rightarrow y$ is decreasing for $x > 1$

for $-1 < x < \frac{1}{2}$, $\frac{dy}{dx} < 0$

$\Rightarrow y$ is decreasing in $[-1, \frac{1}{2}]$

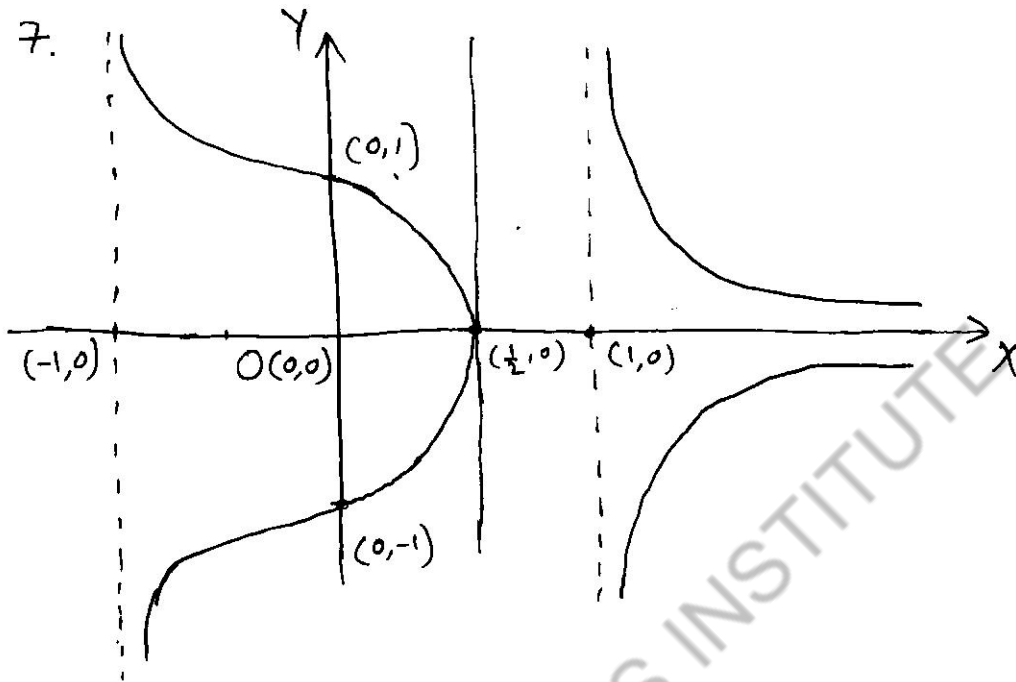


Fig. Curve $y^2(x^2-1) = 2x-1$

Q. 4. c)

Prove that the locus of a line which meets the lines $y = mx, z = c$;

$y = -mx, z = -c$ and the circle $x^2 + y^2 = a^2, z = 0$ is

$$c^2 m^2 (cy - mzx)^2 + c^2 (yz - cmx)^2 = a^2 m^2 (z^2 - c^2)^2$$

Solⁿ:

The given lines are

$$y - mx = 0, \quad z - c = 0 \quad - (1)$$

$$y + mx = 0, \quad z + c = 0 \quad - (2)$$

and the circle is

$$x^2 + y^2 = a^2; \quad z = 0 \quad - (3)$$

Any line intersecting (1) & (2) is

$$\left. \begin{aligned} y - mx + k_1(z - c) &= 0 \\ y + mx + k_2(z + c) &= 0 \end{aligned} \right\} - (4)$$

If it meets the circle (3), we have to eliminate x, y, z from (3) & (4)

putting $z = 0$ in (4), we get

$$y - mx + k_1(-c) = 0$$

$$y + mx + k_2(c) = 0$$

$$\text{Solving } \frac{y}{-mk_2c + mk_1c} = \frac{x}{-ck_1 - ck_2} = \frac{1}{m + m}$$

$$\Rightarrow x = \frac{-(k_1 + k_2)c}{2m}$$

$$y = \frac{c(k_1 - k_2)}{2}$$

putting these values of x, y in (3), we get

$$\frac{c^2(k_1+k_2)^2}{4m^2} + \frac{c^2(k_1-k_2)^2}{4} = a^2$$

$$\Rightarrow c^2(k_1+k_2)^2 + c^2m^2(k_1-k_2)^2 = 4a^2m^2 \quad \text{--- (5)}$$

To find the locus,

eliminate k_1, k_2 from (4) & (5)

$$\therefore \text{(4)} \equiv k_1 = \frac{-(y-mx)}{z-c} = \frac{mx-y}{z-c}$$

$$k_2 = \frac{-(y+mx)}{z+c}$$

substituting these values in (5)

$$\therefore \text{(5)} \Rightarrow c^2 \left[\left(\frac{mx-y}{z-c} \right) + \left(\frac{-mx-y}{z+c} \right) \right]^2 + c^2m^2 \left[\left(\frac{mx-y}{z-c} \right) - \left(\frac{mx+y}{z+c} \right) \right]^2 = 4a^2m^2$$

on simplification we get

$$c^2m^2(cy-mzx)^2 + c^2(yz-cmx)^2 = a^2m^2(z^2-c^2)^2$$

which is the required locus.

Q 5 a)

obtain the solution of the initial value problem $\frac{dy}{dx} - 2xy = 2$, $y(0) = 1$ in the form $y = e^{x^2} [1 + \sqrt{\pi} \operatorname{erf}(x)]$.

solⁿ

$\frac{dy}{dx} - 2xy = 2$ is Linear differential eqⁿ in y .

$$p = -2x \quad q = 2$$

$$IF = e^{\int p dx} = e^{\int -2x dx} = e^{-x^2}$$

Hence solution is

$$y \cdot IF = \int q \cdot IF \, dx + c$$

$$y \cdot e^{-x^2} = \int 2 e^{-x^2} \, dx + c \quad \text{--- (1)}$$

$$y(0) = 1$$

$$\therefore 1 \cdot e^0 = \int 2 e^0 \cdot 0 + c$$

$$\boxed{1 = c}$$

eqⁿ (1) become

$$y \cdot e^{-x^2} = \int 2 e^{-x^2} \, dx + 1$$

$$y = e^{x^2} \left[\int 2 e^{-x^2} \, dx + 1 \right] \quad \text{--- (2)}$$

$$\int e^{-x^2} \, dx = \int_0^x e^{-u^2} \, du \quad \text{--- (3)}$$

$$\text{we know } \operatorname{erf}(x) = \frac{2}{\sqrt{\pi}} \int_0^x e^{-u^2} \, du$$

$$\therefore 2 \int_0^x e^{-u^2} du = \sqrt{\pi} \operatorname{erf}(x) \quad \text{--- (4)}$$

hence by eqⁿ (2), (3) and (4)

$$y = e^{x^2} [1 + \sqrt{\pi} \operatorname{erf}(x)]$$

is required solution.

Q. 5 b)

Given that $L\{f(t); p\} = F(p)$

Show that $\int_0^{\infty} \frac{f(t)}{t} dt = \int_0^{\infty} F(x) dx$.

Hence evaluate the integral $\int_0^{\infty} \frac{e^{-t} - e^{-3t}}{t} dt$.

Solⁿ:

i) Given that $L\{f(t); p\} = F(p)$

We have,

$$L\left\{\frac{f(t)}{t}\right\} = \int_0^{\infty} e^{-st} \frac{f(t)}{t} dt$$

$$= \int_s^{\infty} f(x) dx$$

$$= \int_s^{\infty} F(x) dx$$

$$= \int_s^0 F(x) dx + \int_0^{\infty} F(x) dx$$

$$= -\int_0^s F(x) dx + \int_0^{\infty} F(x) dx \quad \text{--- (1)}$$

Taking limits of both sides of (1) as $s \rightarrow 0^+$ and assuming that the integral converges, we get

$$\int_0^{\infty} \frac{f(t)}{t} dt = \int_0^{\infty} F(x) dx$$

Hence proved.

$$\text{ii) } \int_0^{\infty} \frac{e^{-t} - e^{-3t}}{t} dt$$

$$\Rightarrow L\{e^{-t} - e^{-3t}\}$$

$$= L\{e^{-t}\} - L\{e^{-3t}\}$$

$$= \frac{1}{s+1} - \frac{1}{s+3} = f(s), \text{ say } \text{--- (1)}$$

$$L\left\{\frac{e^{-t} - e^{-3t}}{t}\right\} = \int_s^{\infty} f(s) ds$$

$$= \int_s^{\infty} \left(\frac{1}{s+1} - \frac{1}{s+3}\right) ds, \text{ using (1)}$$

$$= \left[\log(s+1) - \log(s+3)\right]_s^{\infty}$$

$$= \left[\log\left(\frac{s+1}{s+3}\right)\right]_s^{\infty}$$

$$= \lim_{s \rightarrow \infty} \log\frac{s+1}{s+3} - \log\left(\frac{s+1}{s+3}\right)$$

$$= \lim_{s \rightarrow \infty} \log\frac{1 + 1/s}{1 + 3/s} + \log\left(\frac{s+3}{s+1}\right)$$

$$= \log(1) + \log\left(\frac{s+3}{s+1}\right)$$

$$= \log\left(\frac{s+3}{s+1}\right)$$

$$\text{or } \int_0^{\infty} e^{-st} \left(\frac{e^{-t} - e^{-3t}}{t}\right) dt = \log\left(\frac{s+3}{s+1}\right) \text{--- (2)}$$

- by definition of Laplace Transform

Taking limit of both sides of (2)
as $s \rightarrow 0$, we get

$$\int_0^{\infty} \frac{e^{-t} - e^{-3t}}{t} dt = \log\left(\frac{3}{1}\right) = \log 3$$

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Q. 50) A cylinder of radius 'a' touches a vertical wall along a generating line. Axis of the cylinder is fixed horizontally. A uniform flat beam of length 'l' and weight 'w' rests with its extremities in contact with the wall and the cylinder, making an angle of 45° with the vertical. If frictional forces are neglected then show that

$$\frac{a}{l} = \frac{\sqrt{5} + 5}{4\sqrt{2}}$$

Also, find the reactions of the cylinder and wall.

solⁿ \Rightarrow

A given the rod AB is in the position of equilibrium on the cylinder and against the wall under the forces then it must be true below.

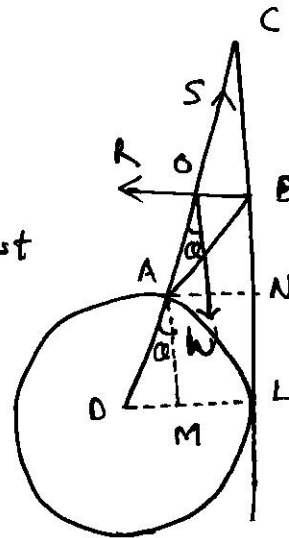


fig. 01

- i) Reaction $R \perp$ wall at B
- ii) Reaction S at A passing through the centre D.
- iii) weight w acting at the middle point G of the rod vertically downwards

$$\angle ABL = \angle OQB = 45^\circ \text{ (Given)}$$

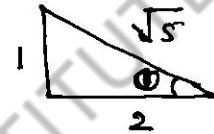
$$\text{Let } \angle AOG = \theta$$

Applying m:n theorem in $\triangle AOB$

$$(1+1) \cot 45^\circ = 1 \cot \theta - 1 \cot 90^\circ$$

$$2 = \cot \theta$$

$$\cot \theta = 2 \quad \text{--- (1)}$$



by applying Lami's theorem

$$\frac{R}{\sin(180-\theta)} = \frac{s}{\sin 90} = \frac{W}{\sin(90+\theta)}$$

$$\frac{R}{\sin \theta} = \frac{s}{1} = \frac{W}{\cos \theta}$$

$$R = W \tan \theta = \frac{W}{2} \text{ since eqn (1)}$$

$$\text{Reaction on the wall } R = \frac{W}{2}$$

$$\begin{aligned} \text{and } s &= W \sec \theta = W \sqrt{1 + \tan^2 \theta} \\ &= W \sqrt{1 + 1/4} = \frac{\sqrt{5}}{2} W \end{aligned}$$

$$DL = DM + ML = DM + AN = a \sin \theta + l \sin 45^\circ$$

$$\Rightarrow a = a \left(\frac{1}{\sqrt{5}} \right) + l \left(\frac{1}{\sqrt{2}} \right)$$

$$\Rightarrow \frac{l}{\sqrt{2}} = \left(\frac{\sqrt{5}-1}{\sqrt{5}} \right) a$$

$$\Rightarrow \frac{a}{l} = \frac{\sqrt{s} \cdot 1}{\sqrt{2} \sqrt{s-1}} = \frac{\sqrt{s}}{\sqrt{2}} \cdot \frac{\sqrt{s+1}}{\sqrt{s-1} \sqrt{s+1}}$$

$$= \frac{\sqrt{s}}{\sqrt{2}} \cdot \frac{\sqrt{s+1}}{4} = \frac{\sqrt{s+1}}{4\sqrt{2}}$$

$$\therefore \boxed{\frac{a}{l} = \frac{s + \sqrt{s}}{4\sqrt{2}}} \quad \text{Hence proved}$$

similar, Reaction on the wall

$$R = w \tan \alpha = w \cdot \left(\frac{1}{2}\right) = \frac{w}{2}$$

$$\therefore \boxed{R = \frac{w}{2}}$$

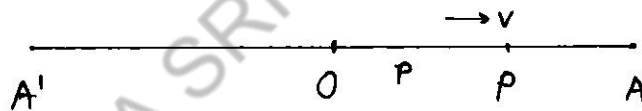
is required solution.

Q. 5 d)

A particle is moving under Simple Harmonic Motion of period T about a centre O . It passes through the point P with velocity v along the direction OP and $OP = p$. Find the time that elapses before the particle returns to the point P . What will be the value of p when the elapsed time is $\frac{T}{2}$?

Solⁿ:

Let the equation of the S.H.M. with centre O as origin be $\frac{d^2x}{dt^2} = -\mu x$



The time period $T = \frac{2\pi}{\sqrt{\mu}}$

Let the amplitude be a .

Then $\left(\frac{dx}{dt}\right)^2 = \mu(a^2 - x^2)$ - (1)

When the particle passes through P its velocity is given to be ' v ' in the direction OP . Also $OP = p$. So putting

$x = p$ and $\frac{dx}{dt} = v$ in (1), we get

$v^2 = \mu(a^2 - p^2)$. - (2)

Let A be an extremity of the motion.
From P the particle comes to instantaneous rest at A and then returns back to P.

In S.H.M. the time from P to A is equal to the time from A to P.

\therefore the required time = $2 \times$ (time from A to P)

Now for the motion from A to P, we have

$$\frac{dx}{dt} = -\sqrt{\mu(a^2 - x^2)} \quad \text{or} \quad dt = -\frac{dx}{\sqrt{\mu(a^2 - x^2)}} \quad \text{--- (3)}$$

Let t_1 be the time from A to P.

Then at A, $t=0$, $x=a$ and at P, $t=t_1$, $x=p$.

Therefore integrating (3), we get

$$t_1 \int_0^1 dt = \frac{1}{\sqrt{\mu}} \int_a^p \frac{-dx}{\sqrt{a^2 - x^2}}$$

$$t_1 = \frac{1}{\sqrt{\mu}} \left[\cos^{-1} \frac{x}{a} \right]_a^p$$

$$\therefore t_1 = \frac{1}{\sqrt{\mu}} \left[\cos^{-1} \frac{p}{a} - \cos^{-1} 1 \right]$$

$$\therefore t_1 = \frac{1}{\sqrt{\mu}} \cos^{-1} \frac{p}{a}$$

Hence the required time

$$= 2t_1$$

$$= \frac{2}{\sqrt{\mu}} \cos^{-1} \frac{p}{a}$$

$$= \frac{2}{\sqrt{\mu}} \tan^{-1} \left(\frac{\sqrt{a^2 - p^2}}{p} \right)$$

$$= \frac{2}{\sqrt{\mu}} \tan^{-1} \left(\frac{v}{p\sqrt{\mu}} \right)$$

$$\left[\because \text{from (2), } \sqrt{a^2 - p^2} = \frac{v}{\sqrt{\mu}} \right]$$

$$= \frac{2}{2\pi/T} \tan^{-1} \left(\frac{v}{p(2\pi/T)} \right)$$

$$\left(\because T = \frac{2\pi}{\sqrt{\mu}} \therefore \sqrt{\mu} = \frac{2\pi}{T} \right)$$

$$= \frac{T}{\pi} \tan^{-1} \left(\frac{vT}{2\pi p} \right)$$

$$\therefore \text{Time elapsed before particle returns to point } p = \frac{T}{\pi} \tan^{-1} \left(\frac{vT}{2\pi p} \right)$$

To find value of p when elapsed time is $\frac{T}{2}$:

$$\therefore \frac{T}{2} = \frac{T}{\pi} \tan^{-1} \left(\frac{vT}{2\pi p} \right)$$

$$\therefore \tan \frac{\pi}{2} = \frac{vT}{2\pi p}$$

$$\infty = \frac{vT}{2\pi p}$$

$$\Rightarrow \boxed{p = 0}$$

Q. 5 e)

$$\text{IF } \vec{a} = \sin\theta \mathbf{i} + \cos\theta \mathbf{j} + \theta \mathbf{k}$$

$$\vec{b} = \cos\theta \mathbf{i} - \sin\theta \mathbf{j} - 3\mathbf{k}$$

$$\vec{c} = 2\mathbf{i} + 3\mathbf{j} - 3\mathbf{k}$$

then find the values of the derivative of the vector function $\vec{a} \times (\vec{b} \times \vec{c})$ w.r. to θ at $\theta = \frac{\pi}{2}$ and $\theta = \pi$

solⁿ

$$\Rightarrow \vec{b} \times \vec{c} = \begin{vmatrix} \mathbf{i} & \mathbf{j} & \mathbf{k} \\ \cos\theta & -\sin\theta & -3 \\ 2 & 3 & -3 \end{vmatrix}$$

$$= \mathbf{i}(3\sin\theta + 9) + \mathbf{j}(-6 + 3\cos\theta) + \mathbf{k}(3\cos\theta + 2\sin\theta)$$

$$\vec{a} \times (\vec{b} \times \vec{c}) = \begin{vmatrix} \mathbf{i} & \mathbf{j} & \mathbf{k} \\ \sin\theta & \cos\theta & \theta \\ 3\sin\theta + 9 & -6 + 3\cos\theta & 3\cos\theta + 2\sin\theta \end{vmatrix}$$

$$= \mathbf{i}(3\cos^2\theta + 2\sin\theta\cos\theta + 6\theta - 3\theta\sin\theta) + \mathbf{j}(3\theta\sin\theta + 9\theta - 3\sin\theta\cos\theta - 2\sin^2\theta) + \mathbf{k}(-6\sin\theta + 3\sin\theta\cos\theta - 3\sin\theta\cos\theta - 9\cos\theta)$$

$$= \mathbf{i}(3\cos^2\theta + 2\sin\theta\cos\theta - 3\theta\sin\theta + 6\theta) + \mathbf{j}(-2\sin^2\theta - 3\sin\theta\cos\theta + 3\theta\sin\theta + 9\theta) + \mathbf{k}(-6\sin\theta - 9\cos\theta)$$

$$\frac{d}{d\theta} (\vec{a} \times (\vec{b} \times \vec{c})) = \mathbf{i}(-6\cos\theta\sin\theta +$$

$$2\cos^2\theta + -2\sin^2\theta - 3\sin\theta - 3\theta\cos\theta + 6) + \mathbf{j}(-2\sin\theta\cos\theta - 3\cos^2\theta + 3\sin^2\theta + 3\theta\cos\theta + 9) + \mathbf{k}(-6\cos\theta + 9\sin\theta)$$

$$\theta = \frac{\pi}{2}, \quad \sin \frac{\pi}{2} = 1 \quad \cos \frac{\pi}{2} = 0$$

$$\frac{d}{d\theta} [\bar{a} \times (\bar{b} \times \bar{c})] = i(-5+6) + j(3+3+9) + k(-9)$$

$$= i + 15j + 9k$$

$$\boxed{\frac{d}{d\theta} [\bar{a} \times (\bar{b} \times \bar{c})] = i + 15j + 9k}$$

$$\theta = \pi, \quad \sin \pi = 0 \quad \cos \pi = -1$$

$$\frac{d}{d\theta} [\bar{a} \times (\bar{b} \times \bar{c})] = i(2+3\pi+6) + j(-3+3\pi+9) + k(6)$$

$$= i(8+3\pi) + j(6-3\pi) + 6k$$

$$\boxed{\frac{d}{d\theta} [\bar{a} \times (\bar{b} \times \bar{c})] = (8+3\pi)i + j(6-3\pi) + 6k}$$

is required solution.

Q. 6 a)

Solve the differential equation:

$$\frac{d^3 y}{dx^3} - 3 \frac{d^2 y}{dx^2} + 4 \frac{dy}{dx} - 2y = e^x + \cos x$$

Solⁿ:

Given $(D^3 - 3D^2 + 4D - 2)y = e^x + \cos x$, - ①

where $D \equiv d/dx$

Its auxiliary equation is

$$D^3 - 3D^2 + 4D - 2 = 0$$

or $D^2(D-1) - 2D(D-1) + 2(D-1) = 0$

or $(D-1)(D^2 - 2D + 2) = 0$

giving $D = 1, \frac{(2 \pm \sqrt{4-8})}{2}$

i.e. $D = 1, 1 \pm i$

\therefore C.F. = $C_1 e^x + e^x (C_2 \cos x + C_3 \sin x)$,

C_1, C_2, C_3 being arbitrary constants

P.I. corresponding to e^x

$$= \frac{1}{D^3 - 3D^2 + 4D - 2} e^x$$

$$= \frac{1}{(D-1)(D^2 - 2D + 2)} e^x$$

$$= \frac{1}{D-1} \cdot \frac{1}{1-2+2} e^x$$

$$= \frac{1}{D-1} e^x \cdot 1$$

$$= e^x \frac{1}{(D+1)-1} \cdot 1$$

$$= e^x \frac{1}{D} \cdot 1$$

$$= x e^x$$

P. I. corresponding to $\cos x$

$$= \frac{1}{D^3 - 3D^2 + 4D - 2} \cos x$$

$$= \frac{1}{D^2 \cdot D - 3D^2 + 4D - 2} \cos x$$

$$= \frac{1}{(-1^2)D - 3(-1^2) + 4D - 2} \cos x$$

$$= \frac{1}{3D+1} \cos x = (3D-1) \frac{1}{9D^2-1} \cos x$$

$$= (3D-1) \frac{1}{9(-1^2)-1} \cos x$$

$$= \frac{-1}{10} (3D \cos x - \cos x)$$

$$= \frac{-1}{10} (-3 \sin x - \cos x) = \frac{3 \sin x + \cos x}{10}$$

∴ Required solution is

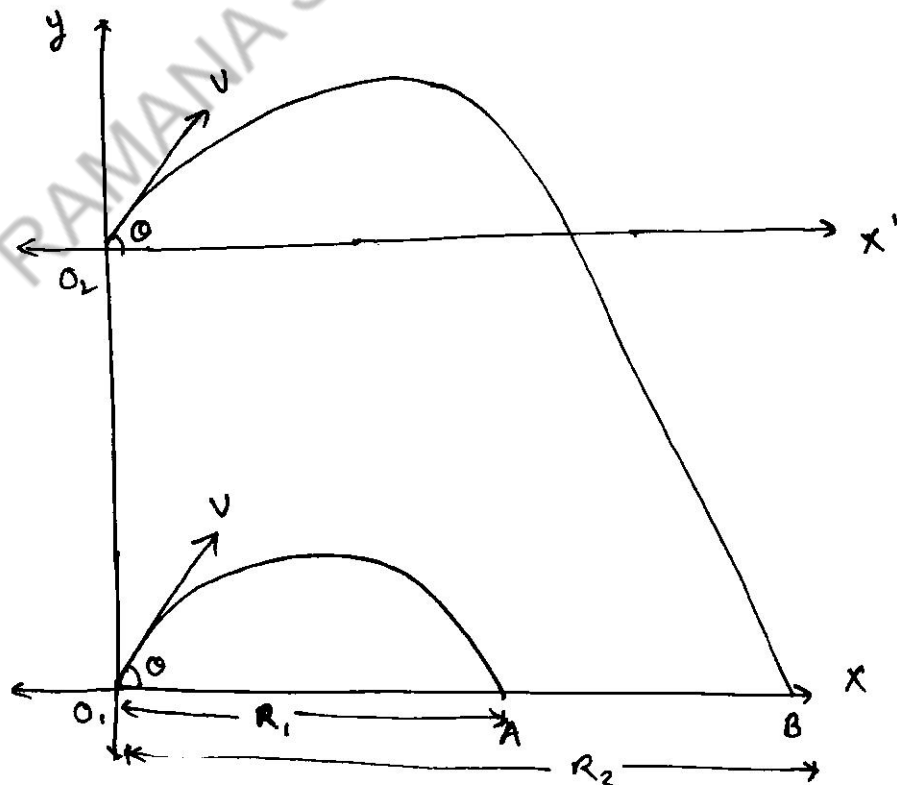
$$y = e^x (C_1 + C_2 \cos x + C_3 \sin x) + x e^x + \frac{3 \sin x + \cos x}{10}$$

Q. 6b)

When a particle is projected from a point O_1 on the sea level with a velocity V and angle of projection θ with the horizontal horizon in a vertical plane, its horizontal range is R_1 . If it is further projected from a point O_2 , which is vertically above O_1 , at a height h in the same vertical plane, with the same velocity V and same angle θ with the horizon, its horizontal range is R_2 . Prove that $R_2 > R_1$ and $(R_2 - R_1) : R_1$ is equal to

$$\frac{1}{2} \left\{ \sqrt{\left(1 + \frac{2gh}{V^2 \sin^2 \theta}\right)} - 1 \right\} : 1$$

solⁿ ⇒



let R_1 be the original range. then

$$R_1 = \frac{2v^2 \sin\theta \cos\theta}{g}$$

let O be a point a height h above the water level. let R_2 be the range on the sea when the shot is fired from O .

Refered to the horizontal and vertical lines OX & OY in the plane of projection as the co-ordinates axes of the points P where the shot strikes the water are $(R_1, -h)$ (R_2, h)

the point $(R_1, -h)$ (R_2, h) lies on the curve

$$y = x \tan\theta - \frac{1}{2} \frac{g x^2}{v^2 \cos^2\theta}$$

$$-h = R_2 \tan\theta - \frac{1}{2} \frac{g R_2^2}{v^2 \cos^2\theta}$$

$$\text{or } R_2^2 - \frac{2}{g} v^2 \sin\theta \cos\theta R_2 - \frac{2}{g} v^2 h \cos^2\theta = 0$$

$$R_2^2 - R_2 R_1 - \frac{2}{g} v^2 h \cos^2\theta = 0$$

$$R_2^2 - R_2 R_1 = \frac{2}{g} v^2 h \cos^2\theta$$

$$(R_2 - \frac{1}{2} R_1)^2 = \frac{1}{4} R_1^2 + \frac{2}{g} v^2 h \cos^2\theta =$$

$$= \frac{R_1^2}{4} \left[1 + \frac{1}{R_1^2} \cdot \frac{8}{g} v^2 h \cos^2 \theta \right]$$

$$\therefore (R_2 - \frac{1}{2} R_1)^2 = \frac{R_1^2}{4} \left[1 + \frac{g^2}{4v^2 \sin^2 \theta \cos^2 \theta} \cdot \frac{8}{g} v^2 h \cos^2 \theta \right]$$

[by (1)]

$$= \frac{R_1^2}{4} \left[1 + \frac{2gh}{v^2 \sin^2 \theta} \right]$$

$$R_2 - \frac{1}{2} R_1 = \frac{1}{2} R_1 \left[1 + \frac{2gh}{v^2 \sin^2 \theta} \right]^{1/2}$$

so that,

$$R_2 - R_1 = \frac{1}{2} R_1 \left(1 + \frac{2gh}{v^2 \sin^2 \theta} \right)^{1/2} - \frac{1}{2} R_1$$

$$\frac{R_2 - R_1}{R_1} = \frac{1}{2} \left[\left(1 + \frac{2gh}{v^2 \sin^2 \theta} \right)^{1/2} - 1 \right]$$

hence we proved required result.

Q. 6 (c)

Evaluate the integral $\iint_S (3y^2z^2\hat{i} + 4z^2x^2\hat{j} + z^2y^2\hat{k}) \cdot \hat{n} \, dS$

where S is the upper part of the surface $4x^2 + 4y^2 + 4z^2 = 1$ above the plane $z = 0$ and bounded by the xy -plane. Hence verify Gauss divergence theorem.

Solⁿ → by divergence theorem,

$$\iint_S (3y^2z^2\hat{i} + 4z^2x^2\hat{j} + z^2y^2\hat{k}) \cdot \hat{n} \, dS$$

$$= \iiint_V \text{div} (3y^2z^2\hat{i} + 4z^2x^2\hat{j} + z^2y^2\hat{k}) \, dV$$

where V is the volume enclosed by S .

$$= \iiint_V \left[\frac{\partial}{\partial x} (3y^2z^2) + \frac{\partial}{\partial y} (4z^2x^2) + \frac{\partial}{\partial z} (z^2y^2) \right] \, dV$$

$$= \iiint_V 2zy^2 \, dV = 2 \iiint_V zy^2 \, dV$$

We shall use spherical polar co-ordinates (r, θ, ϕ) to evaluate this triple integral.

In polar,

$$dV = dr, r d\theta, r \sin\theta d\phi$$

$$= r^2 \sin\theta \, dr d\theta d\phi.$$

~~Ans.~~ Also $z = r \cos \theta$, $y = r \sin \theta \sin \phi$

To cover V the limits of r will be 0 to $\frac{1}{2}$, those of θ will be 0 to

$\frac{\pi}{2}$ and those of ϕ will be 0 to 2π .

The triple integral is

$$= 2 \int_{r=0}^{1/2} \int_{\theta=0}^{\pi/2} \int_{\phi=0}^{2\pi} r \cos \theta \cdot r^2 \sin^2 \theta \sin^2 \phi \times r^2 \sin \theta \, dr \, d\theta \, d\phi$$

$$= 2 \int_0^{1/2} \int_0^{\pi/2} \int_0^{2\pi} r^5 \sin^3 \theta \cos \theta \sin^2 \phi \, dr \, d\theta \, d\phi$$

$$= 2 \left(\frac{r^6}{6} \right)_0^{1/2} \int_0^{\pi/2} \int_0^{2\pi} \cos \theta \sin^3 \theta \sin^2 \phi \, d\theta \, d\phi$$

$$= 2 \times \frac{1}{6} \times \frac{1}{2^6} \times \frac{2}{4 \cdot 2} \int_0^{2\pi} \sin^2 \phi \, d\phi$$

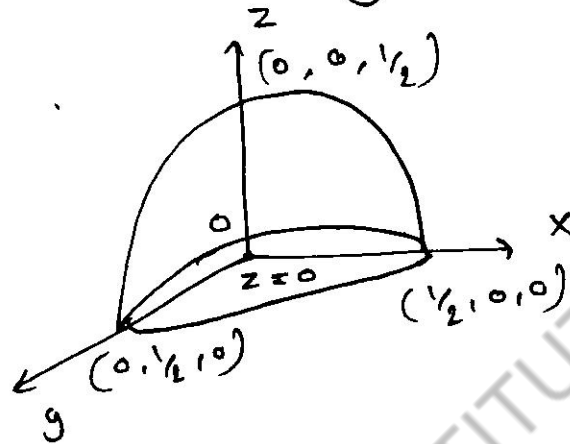
$$= \frac{1}{768} \times 4 \times \int_0^{\pi/2} \sin^2 \phi \, d\phi$$

$$= \frac{1}{768} \times 4 \times \frac{1}{2} \times \frac{\pi}{4}$$

$$= \frac{\pi}{768}$$

$$\boxed{V = \frac{\pi}{768}} \quad \text{--- (1)}$$

verification of Gauss divergence —
 given —



given $\phi \equiv 4x^2 + 4y^2 + 4z^2 - 1 = 0$

let $\vec{F} = 3y^2z^2 \mathbf{i} + 4z^2x^2 \mathbf{j} + z^2y^2 \mathbf{k}$

we have, $\hat{n} = \frac{\nabla\phi}{|\nabla\phi|} = 2(x\mathbf{i} + y\mathbf{j} + z\mathbf{k})$

$\vec{F} \cdot \hat{n} = 2(3xy^2z^2 + 4x^2z^2y + z^3y^2)$

we have $ds = \frac{dx dy}{|\hat{n} \cdot \mathbf{k}|} = \frac{dx dy}{2z}$

$\iint_S \vec{F} \cdot \hat{n} ds = \iint_R \frac{2(3x^2y^2z^2 + 4x^2yz^2 + y^2z^3)}{2z} dx dy$

$= \iint_R (3xy^2z + 4x^2yz + y^2z^2) dx dy \quad \text{--- (1)}$

corresponding to $x^2 + y^2 = \frac{1}{4}$

$x = r \cos\theta$; $y = r \sin\theta$

$\therefore dx dy = r dr d\theta$, $0 \leq r \leq \frac{1}{2}$
 $0 \leq \theta \leq 2\pi$

$$\therefore x^2 + y^2 + z^2 = \frac{1}{4} \Rightarrow z^2 = \frac{1}{4} - x^2 - y^2$$

$$\Rightarrow z = \sqrt{\frac{1}{4} - r^2}$$

$$\therefore \iint_S \vec{P} \cdot \hat{n} \, d\omega = \int_{r=0}^{\frac{1}{2}} \int_{\theta=0}^{2\pi} \left[3r^3 \cos\theta \sin^2\theta \right.$$

$$\left. \times \sqrt{\frac{1}{4} - r^2} + 4r^3 \cos^2\theta \sin\theta \sqrt{\frac{1}{4} - r^2} \right. \\ \left. + r^2 \sin^2\theta \left(\frac{1}{4} - r^2 \right) \right] r \, dr \, d\theta$$

$$= \int_{r=0}^{\frac{1}{2}} \int_{\theta=0}^{2\pi} \left[r^4 \sqrt{\frac{1}{4} - r^2} \left(3 \cos\theta \sin^2\theta + 4 \cos^2\theta \sin\theta \right) \right. \\ \left. + \frac{r^3 \sin^2\theta}{4} - r^5 \sin^2\theta \right] dr \, d\theta$$

$$= \int_0^{2\pi} \left[\sin^2\theta \left(\frac{1}{16 \times 2^4} - \frac{1}{2^{\cancel{24}} \times 6} \right) \right] d\theta$$

$$+ \int_{r=0}^{\frac{1}{2}} r^4 \sqrt{\frac{1}{4} - r^2} \left(\int_{\theta=0}^{2\pi} 3 \cos\theta \sin^2\theta \right. \\ \left. + 4 \cos^2\theta \sin\theta \right) d\theta$$

$$= \frac{\pi}{768} \quad \text{--- (2)}$$

by (1) & (2) we verified Gauss divergence theorem.

Q. 7 a) i)

Find the solution of the differential

$$\text{equation: } \frac{dy}{dx} = \frac{-2xy^3 + 2}{3x^2y^2 + 8e^{4y}}$$

Solⁿ:

$$\frac{dy}{dx} = \frac{-2xy^3 + 2}{3x^2y^2 + 8e^{4y}}$$

$$(2xy^3 + 2) dx + (3x^2y^2 + 8e^{4y}) dy = 0$$

$$M dx + N dy = 0$$

$$\therefore M = 2xy^3 + 2 \quad N = 3x^2y^2 + 8e^{4y}$$

$$\frac{\partial M}{\partial y} = 6xy^2 \quad ; \quad \frac{\partial N}{\partial x} = 6xy^2$$

$$\therefore \frac{\partial M}{\partial y} = 6xy^2 = \frac{\partial N}{\partial x}$$

Hence above ODE is exact.

Therefore solution is

$$\int_{y=c} M dx + \int N dy = c$$

no x term

$$\int_{y=c} (2xy^3 + 2) dx + \int 8e^{4y} dy = c$$

$$\Rightarrow 2y^3 \frac{x^2}{2} + 2x + 8 \frac{e^{4y}}{4} = c$$

$$\boxed{x^2y^3 + 2x + 2e^{4y} = c}$$

which is the required solution.

Q. 7 a) ii)

Reduce the equation $x^2 p^2 + y(2x+y) p + y^2 = 0$ to Clairaut's form by the substitution $y = u$ and $xy = v$. Hence solve the equation and show that $y+4x=0$ is a singular solution of the differential equation.

Solⁿ:

Given equation is $x^2 p^2 + y p(2x+y) + y^2 = 0$ - (1)

Given $y = u$ and $xy = v$. - (2)

Differentiating (2)

$$dy = du \quad \text{and} \quad x dy + y dx = dv$$

$$\therefore \frac{x dy + y dx}{dy} = \frac{dv}{du}$$

$$\text{or } x + y \frac{dx}{dy} = \frac{dv}{du}$$

$$\text{or } x + \frac{y}{p} = p$$

$$\text{or } \frac{y}{p} = p - x$$

$$\text{or } p = \frac{y}{(p-x)} \quad \text{where } p = \frac{dy}{dx}, \quad P = \frac{dv}{du}$$

putting $p = y/(p-x)$ in (1), we have

$$\frac{x^2 y^2}{(p-x)^2} + \frac{y^2}{p-x} (2x+y) + y^2 = 0$$

$$\text{or } x^2 + (p-x)(2x+y) + (p-x)^2 = 0$$

or $P_y - xy + P^2 = 0$

or $v = uP + P^2$ using ② - ③

③ is in Clairaut's form.

So replacing P by c its general solution

is $v = uc + c^2$

or $xy = yc + c^2$, c being an arbitrary constant.

or $c^2 + cy - xy = 0$

which is a quadratic equation in c

and hence c -discriminant relation is

$y^2 - 4 \cdot 1 \cdot (-xy) = 0$

or $y(y + 4x) = 0$

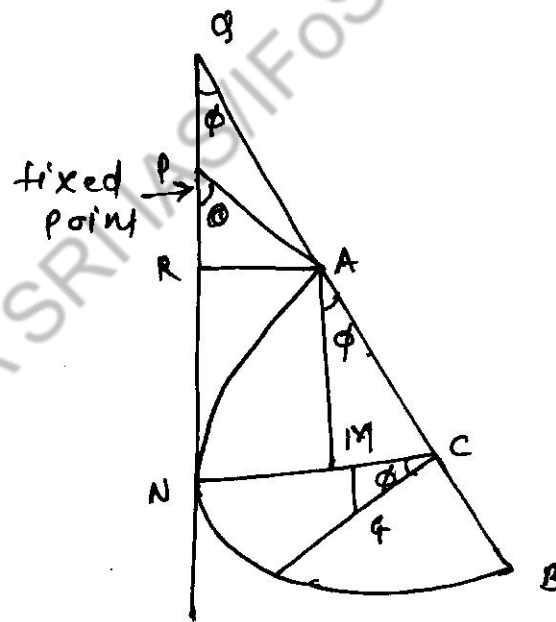
Since $y = 0$ and $y + 4x = 0$ both satisfy ①,

so these are both singular solutions.

Q.7 (b)

A solid hemisphere is supported by a string fixed to a point on its rim and to a point on a smooth vertical wall with which the curved surface is in contact. If θ is the angle of inclination of the string with vertical and ϕ is the angle of inclination of the plane base of the hemisphere to the vertical, then find the value of $(\tan \phi - \tan \theta)$.

Solⁿ ⇒



let the length of the string $AP = l$
 and let the radius of the hemisphere be a so that $lG = \frac{3a}{8}$

P is a fixed point in the wall. Give a small displacement to the system such that θ and ϕ become $\theta + \delta\theta$ and $\phi + \delta\phi$ respectively.

Equation of virtual work is
 $w \delta$ (depth of G below P) = 0
 or δ (depth of G below P) = 0

$$\delta (PR + RN + MQ) = 0$$

$$\text{or } \delta (l \cos \theta + a \cos \phi + \frac{3a}{8} \sin \phi) = 0$$

$$\text{or } -l \sin \theta \delta \theta + \delta \phi \left(-a \sin \phi + \frac{3a}{8} \cos \phi \right) = 0 \dots \dots \dots (1)$$

from the figure it is clear that

$$CN = CL + LN = a \sin \phi + l \sin \theta$$

$$a = a \sin \phi + l \sin \theta$$

taking differential $a \cos \phi \cdot \delta \phi +$

$$l \cos \theta \delta \theta = 0$$

$$\frac{\delta \theta}{\delta \phi} = - \frac{a \cos \phi}{l \cos \theta}$$

using this in (1) we get

$$-l \sin \theta \cdot \left(\frac{-a \cos \phi}{l \cos \theta} \right) +$$

$$\left(-a \sin \phi + \frac{3a}{8} \cos \phi \right) = 0$$

$$\tan \theta \cdot \cos \phi - \sin \phi + \frac{3}{8} \cos \phi = 0$$

dividing by $\cos \phi$,

$$\tan \theta - \tan \phi + \frac{3}{8} = 0$$

$$\tan \phi - \tan \theta = \frac{3}{8}$$

Hence required solution

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Q. 7 c)

If the tangent to a curve makes a constant angle θ with a fixed line, then prove that the ratio of radius of torsion to radius of curvature is proportional to $\tan \theta$. Further prove that if this ratio is constant, then the tangent makes a constant angle with a fixed direction.

Solⁿ:

Let's consider a curve in 3-D space parametrized by arc length, denoted by $\vec{r}(s)$, where s is the arc length parameter. The radius of curvature R is given by:

$$R = \left| \frac{d\vec{T}}{ds} \right|^{-1}$$

where \vec{T} is the unit tangent vector to the curve.

Now, let's consider the tangent vector $\vec{T}(s)$ at a point on the curve.

According to the problem, the tangent makes a constant angle θ with a fixed line. This means that $\vec{T}(s)$ is rotating about a fixed axis with a constant angular velocity ω , such that

$$\theta = \omega s$$

Differentiating $\vec{T}(s)$ with respect to s gives us $\frac{d\vec{T}}{ds} = \omega \vec{N}$, where \vec{N} is the unit normal vector.

Now, the radius of torsion T is defined as the reciprocal of the rate of change of θ w.r.t. arc length s :

$$T = \left| \frac{d\theta}{ds} \right|^{-1} = \left| \frac{d(\omega s)}{ds} \right|^{-1} = |\omega|^{-1}$$

Now, the radius

So, we have found expressions for both the radius of curvature and the radius of torsion.

Now, let's examine the relationship between T and R :

$$\frac{T}{R} = |\omega|^{-1} \cdot \left| \frac{d\vec{T}}{ds} \right|^{-1}$$

Since $\left| \frac{d\vec{T}}{ds} \right| = |\omega \vec{N}| = |\omega| \cdot |\vec{N}| = |\omega|$,

we can simplify the expression:

$$\boxed{\frac{T}{R} = |\omega|^{-1} \cdot |\omega|^{-1} = |\omega|^{-2} = \tan^2(\theta)}$$

So, we have proved that the ratio of the radius of torsion to radius of curvature is proportional to $\tan^2(\theta)$.

Now, let's prove the second part of the statement.

If this ratio $\frac{I}{R}$ is constant, it implies that $\tan^2(\theta)$ is constant.

Since $\tan^2(\theta)$ is constant, θ must be constant as well, because the tangent of a constant angle is also a constant.

Therefore, if the ratio $\frac{I}{R}$ is constant, the tangent makes a constant angle θ with a fixed direction.

Q. 8 a) Solve the following initial value problem by using Laplace transform technique:

$$\frac{d^2 y}{dt^2} - 4 \frac{dy}{dt} + 3y(t) = f(t),$$

$y(0) = 1$, $y'(0) = 0$ and $f(t)$ is a given function of t .

Solⁿ: Given $y'' - 4y' + 3y = f(t)$ - ①

where $y'' = \frac{d^2 y}{dt^2}$, $y' = \frac{dy}{dt}$

with initial condition

$y(0) = 1$ and $y'(0) = 0$ - ②

Taking Laplace transform of both sides of ①, we get

$$L\{y''\} - 4L\{y'\} + 3L\{y\} = L\{f(t)\}$$

$$\text{or } s^2 L\{y\} - sy(0) - y'(0) - 4[sL\{y\} - y(0)] + 3L\{y\} = f(s) \quad - \text{③}$$

where $L\{f(t)\} = f(s)$ so that $L^{-1}\{f(s)\} = f(t)$ - ④

Using ②,

$$\text{③} \Rightarrow (s^2 - 4s + 3)L\{y\} - s + 4 = f(s)$$

$$\begin{aligned} \text{or } L\{y\} &= \frac{s - 4 + f(s)}{(s^2 - 4s + 3)} \\ &= \frac{s - 4}{(s-1)(s-3)} + \frac{f(s)}{(s-1)(s-3)} \end{aligned}$$

$$\text{or } L\{y\} = \frac{1}{2} \left[\frac{3}{s-1} - \frac{1}{s-3} \right] + \frac{1}{2} f(s) \left[\frac{1}{s-3} - \frac{1}{s-1} \right]$$

on resolving into partial fractions

$$\begin{aligned} \therefore y &= \frac{3}{2} L^{-1} \left\{ \frac{1}{s-1} \right\} - \frac{1}{2} L^{-1} \left\{ \frac{1}{s-3} \right\} + \frac{1}{2} L^{-1} \left\{ f(s) \frac{1}{s-3} \right\} \\ &\quad - \frac{1}{2} L^{-1} \left\{ f(s) \frac{1}{s-1} \right\} \end{aligned}$$

$$\begin{aligned} y &= \frac{3}{2} e^t - \frac{1}{2} e^{3t} + \frac{1}{2} L^{-1} \{ f(s) g(s) \} \\ &\quad - \frac{1}{2} L^{-1} \{ f(s) h(s) \} \quad - (5) \end{aligned}$$

$$\text{where } g(s) = \frac{1}{s-3} \quad \text{and} \quad h(s) = \frac{1}{s-1} \quad - (6)$$

$$\begin{aligned} \text{so that } g(t) &= L^{-1} \{ g(s) \} = e^{3t} \\ \text{and } h(t) &= L^{-1} \{ h(s) \} = e^t \end{aligned} \quad \} (7)$$

Now, by using the convolution theorem and (7), we have

$$\begin{aligned} L^{-1} \{ f(s) g(s) \} &= \int_0^t f(u) g(t-u) du \\ &= \int_0^t f(u) e^{3(t-u)} du \\ &= e^{3t} \int_0^t f(u) e^{-3u} du \quad - (8) \end{aligned}$$

$$\begin{aligned} \text{and } L^{-1} \{ f(s) h(s) \} &= \int_0^t f(u) h(t-u) du \\ &= \int_0^t f(u) e^{t-u} du \\ &= e^t \int_0^t f(u) e^{-u} du \quad - (9) \end{aligned}$$

Using (8) and (9), (5) reduces to

$$y = \frac{1}{2} (3e^t - e^{3t}) + \frac{1}{2} e^{3t} \int_0^t f(u) e^{-3u} du$$
$$- \frac{1}{2} e^t \int_0^t f(u) e^{-u} du$$

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Q. 8. b)

A particle is projected from an apse at a distance \sqrt{c} from the centre of force with a velocity $\sqrt{\frac{2\lambda c^3}{3}}$ and is moving with central acceleration $\lambda(r^5 - c^2r)$. Find the path of motion of this particle. Will that be the curve $x^4 + y^4 = c^2$?

Solⁿ:

Here the central acceleration

$$P = \lambda(r^5 - c^2r) = \lambda\left(\frac{1}{u^5} - \frac{c^2}{u}\right)$$

\therefore The differential equation of the path is

$$\begin{aligned} h^2 \left[u + \frac{d^2u}{d\theta^2} \right] &= \frac{P}{u^2} \\ &= \frac{\lambda}{u^2} \left(\frac{1}{u^5} - \frac{c^2}{u} \right) \\ &= \lambda \left(\frac{1}{u^7} - \frac{c^2}{u^3} \right) \end{aligned}$$

Multiplying both sides by $2 \left(\frac{du}{d\theta} \right)$ and then integrating, we have

$$v^2 = h^2 \left(u^2 + \left(\frac{du}{d\theta} \right)^2 \right) = \lambda \left[\frac{-1}{3u^6} + \frac{c^2}{u^2} \right] + A \quad \text{--- (1)}$$

where A is constant.

But initially, when $r = \sqrt{c}$ i.e. $u = \frac{1}{\sqrt{c}}$

$$\frac{du}{d\theta} = 0 \quad (\text{at an apse}) \quad \text{and}$$

$$v = \sqrt{\frac{2\lambda c^3}{3}}$$

\therefore from (1), we have

$$\left(\sqrt{\frac{2\lambda}{3}c^3}\right)^2 = h^2 \left(\frac{1}{\sqrt{c}}\right)^2 = \lambda \left(-\frac{c^3}{3} + c^3\right) + A$$

$$\frac{2\lambda c^3}{3} = \frac{h^2}{c} = \lambda \frac{2c^3}{3} + A$$

$$\therefore A = 0 \text{ and } h^2 = \frac{2\lambda c^4}{3}$$

Substituting the values of h^2 and A in ①, we have

$$\frac{2\lambda}{3}c^4 \left[u^2 + \left(\frac{dy}{dx}\right)^2 \right] = \lambda \left(\frac{-1}{3u^6} + \frac{c^2}{u^2} \right)$$

$$c^4 \left[u^2 + \left(\frac{dy}{dx}\right)^2 \right] = \frac{3}{2} \left(\frac{-1}{3u^6} + \frac{c^2}{u^2} \right)$$

$$c^4 \left(\frac{dy}{dx}\right)^2 = \frac{-1}{2u^6} + \frac{3c^2}{2u^2} - c^4 u^2$$

$$= \frac{1}{u^6} \left[\frac{-1}{2} + \frac{3}{2}c^2 u^4 - c^4 u^8 \right]$$

$$= \frac{1}{u^6} \left[\frac{-1}{2} - \left(c^4 u^8 - \frac{3}{2}c^2 u^4 \right) \right]$$

$$= \frac{1}{u^6} \left[\frac{-1}{2} - \left(c^2 u^4 - \frac{3}{4} \right)^2 + \frac{9}{16} \right]$$

$$= \frac{1}{u^6} \left[\frac{1}{16} - \left(c^2 u^4 - \frac{3}{4} \right)^2 \right]$$

$$= \frac{1}{u^6} \left[\left(\frac{1}{4} \right)^2 - \left(c^2 u^4 - \frac{3}{4} \right)^2 \right]$$

$$\therefore c^2 u^3 \left(\frac{dy}{dx}\right) = \sqrt{\left(\frac{1}{4}\right)^2 - \left(c^2 u^4 - \frac{3}{4}\right)^2}$$

$$d\theta = \frac{c^2 u^3 du}{\sqrt{\left(\frac{1}{4}\right)^2 - \left(c^2 u^4 - \frac{3}{4}\right)^2}} \quad - (2)$$

Putting $c^2 u^4 - \frac{3}{4} = z \Rightarrow 4c^2 u^3 du = dz$
 $c^2 u^3 du = \frac{1}{4} dz$

$$\therefore (2) \Rightarrow 4 d\theta = \frac{dz}{\sqrt{\left(\frac{1}{4}\right)^2 - z^2}}$$

Integrating,

$$4\theta + B = \sin^{-1}\left(\frac{z}{\frac{1}{4}}\right) = \sin^{-1}(4z)$$

where B is constant.

$$4\theta + B = \sin^{-1}(4c^2 u^4 - 3)$$

But initially when $u = \frac{1}{\sqrt{c}}$, $\theta = 0$

$$\therefore B = \sin^{-1}(1) = \frac{\pi}{2}$$

$$\therefore 4\theta + \frac{\pi}{2} = \sin^{-1}(4c^2 u^4 - 3)$$

$$\sin\left(4\theta + \frac{\pi}{2}\right) = 4c^2 u^4 - 3$$

$$\cos 4\theta = 4c^2 u^4 - 3$$

$$4c^2 u^4 = 3 + \cos 4\theta$$

$$4 \frac{c^2}{r^4} = 3 + \cos 4\theta$$

$$4c^2 = r^4 [3 + (2\cos^2 2\theta - 1)]$$

$$4c^2 = 2r^4 [1 + \cos^2 2\theta]$$

$$4c^2 = 2r^4 [(\cos^2 \theta + \sin^2 \theta)^2 + (\cos^2 \theta - \sin^2 \theta)^2]$$

$$4c^2 = 4r^4 [\cos^4\theta + \sin^4\theta]$$

$$c^2 = (r\cos\theta)^4 + (r\sin\theta)^4$$

$$c^2 = x^4 + y^4$$

which is the required equation of the path.

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Q. 8. c)

For a scalar point function ϕ and vector point function \vec{f} , prove the identity $\nabla \cdot (\phi \vec{f}) = \nabla \phi \cdot \vec{f} + \phi (\nabla \cdot \vec{f})$. Also find the value of $\nabla \cdot \left(\frac{f(r)}{r} \vec{r} \right)$ and then verify stated identity.

Solⁿ :

i) We have,

$$\text{div}(\phi \vec{f}) = \nabla \cdot (\phi \vec{f})$$

$$= \left(i \frac{\partial}{\partial x} + j \frac{\partial}{\partial y} + k \frac{\partial}{\partial z} \right) \cdot (\phi \vec{f})$$

$$= i \cdot \frac{\partial}{\partial x} (\phi \vec{f}) + j \cdot \frac{\partial}{\partial y} (\phi \vec{f}) + k \cdot \frac{\partial}{\partial z} (\phi \vec{f})$$

$$= \sum \left\{ i \cdot \left(\frac{\partial}{\partial x} (\phi \vec{f}) \right) \right\}$$

$$= \sum \left\{ i \cdot \left(\frac{\partial \phi}{\partial x} \vec{f} + \phi \frac{\partial \vec{f}}{\partial x} \right) \right\}$$

$$= \sum \left\{ i \cdot \left(\frac{\partial \phi}{\partial x} \vec{f} \right) \right\} + \sum \left\{ i \cdot \left(\phi \frac{\partial \vec{f}}{\partial x} \right) \right\}$$

$$= \sum \left\{ \left(\frac{\partial \phi}{\partial x} i \right) \cdot \vec{f} \right\} + \sum \left\{ \phi \left(i \cdot \frac{\partial \vec{f}}{\partial x} \right) \right\}$$

$$\left[\because a \cdot (mb) = (ma) \cdot b = m(a \cdot b) \right]$$

$$= \left\{ \sum \frac{\partial \phi}{\partial x} i \right\} \cdot \vec{f} + \phi \sum \left(i \cdot \frac{\partial \vec{f}}{\partial x} \right)$$

$$= \nabla \phi \cdot \vec{f} + \phi (\nabla \cdot \vec{f})$$

Hence proved

$$\text{ii) } \nabla \cdot \left(\frac{f(r)}{r} \vec{r} \right)$$

$$= \nabla \cdot \left\{ \frac{f(r)}{r} (x\mathbf{i} + y\mathbf{j} + z\mathbf{k}) \right\}$$

$$= \frac{\partial}{\partial x} \left\{ \frac{f(r)}{r} x \right\} + \frac{\partial}{\partial y} \left\{ \frac{f(r)}{r} y \right\} + \frac{\partial}{\partial z} \left\{ \frac{f(r)}{r} z \right\} \quad \text{--- (1)}$$

$$\text{Now } \frac{\partial}{\partial x} \left\{ \frac{f(r)}{r} x \right\} = \frac{f(r)}{r} + x \frac{d}{dr} \left\{ \frac{f(r)}{r} \right\} \frac{\partial r}{\partial x}$$

$$= \frac{f(r)}{r} + x \left\{ \frac{f'(r)}{r} - \frac{1}{r^2} f(r) \right\} \frac{x}{r}$$

$$= \frac{f(r)}{r} + \frac{x^2}{r^2} f'(r) - \frac{x^2}{r^3} f(r)$$

$$\text{Similarly } \frac{\partial}{\partial y} \left\{ \frac{f(r)}{r} y \right\} = \frac{f(r)}{r} + \frac{y^2}{r^2} f'(r) - \frac{y^2}{r^3} f(r)$$

$$\text{and } \frac{\partial}{\partial z} \left\{ \frac{f(r)}{r} z \right\} = \frac{f(r)}{r} + \frac{z^2}{r^2} f'(r) - \frac{z^2}{r^3} f(r)$$

putting these values in (1), we get,

$$\nabla \cdot \left(\frac{f(r)}{r} \vec{r} \right) = \frac{3}{r} f(r) + \frac{r^2}{r^2} f'(r) - \frac{r^2}{r^3} f(r)$$

$$= \frac{2}{r} f(r) + f'(r)$$

$$= \frac{1}{r^2} [2r f(r) + r^2 f'(r)]$$

$$= \frac{1}{r^2} \frac{d}{dr} [r^2 f(r)] \quad \text{--- (2)}$$

To verify stated :-

$$\phi = \frac{f(r)}{r} \quad \vec{f} = \vec{r}$$

$$\nabla \cdot (\phi \vec{f}) = \nabla \cdot \left(\frac{f(r)}{r} \vec{r} \right)$$

$$= \frac{1}{r^2} \frac{d}{dr} [r^2 f(r)] \quad \text{- from (2)}$$

$$\text{i.e. L.H.S} = \nabla \cdot (\phi \vec{f}) = \frac{1}{r^2} \frac{d}{dr} [r^2 f(r)]$$

$$\text{R.H.S.} = \nabla \phi \cdot \vec{f} + \phi (\nabla \cdot \vec{f})$$

$$= \nabla \left(\frac{f(r)}{r} \right) \cdot \vec{r} + \frac{f(r)}{r} (\nabla \cdot \vec{r})$$

$$= \left[\nabla f(r) \left(\frac{1}{r} \right) + f(r) \nabla \left(\frac{1}{r} \right) \right] \cdot \vec{r} + \frac{3f(r)}{r}$$

$$= \left[\frac{f'(r)}{r} \nabla r + f(r) \left(\frac{-\vec{r}}{r^3} \right) \right] \cdot \vec{r} + \frac{3f(r)}{r}$$

$$= \left[\frac{f'(r)}{r^2} \vec{r} - \frac{f(r)}{r^3} \vec{r} \right] \cdot \vec{r} + \frac{3f(r)}{r}$$

$$= \left[\frac{f'(r)}{r^2} - \frac{f(r)}{r^3} \right] (\vec{r} \cdot \vec{r}) + \frac{3f(r)}{r}$$

$$= \left(\frac{f'(r)}{r^2} - \frac{f(r)}{r^3} \right) r^2 + \frac{3f(r)}{r}$$

$$= f'(r) - \frac{f(r)}{r} + \frac{3f(r)}{r}$$

$$= f'(r) + \frac{2f(r)}{r}$$

$$= \frac{1}{r^2} [r^2 f'(r) + 2r f(r)]$$

$$= \frac{1}{r^2} \frac{d}{dr} [r^2 f(r)]$$

$$\therefore \text{L.H.S.} = \text{R.H.S.}$$

Hence stated identity

$$\text{i.e. } \nabla \cdot (\phi \vec{F}) = \nabla \phi \cdot \vec{F} + \phi (\nabla \cdot \vec{F})$$

is verified.